LECTURE 17

Algorithms for Polynomial Interpolation

We have thus far three algorithms for determining the polynomial interpolation of a given set of data.

1. Brute Force Method. Set

$$P(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$$

and solve the following set of n + 1 equations

$$a_{n} (x_{0})^{n} + a_{n-1} (x_{0})^{n-1} + \dots + a_{1} x_{0} + a_{0} = y_{0}$$

$$a_{n} (x_{1})^{n} + a_{n-1} (x_{1})^{n-1} + \dots + a_{1} x_{1} + a_{0} = y_{1}$$

$$\vdots$$

$$a_{n} (x_{n})^{n} + a_{n-1} (x_{n})^{n-1} + \dots + a_{1} x_{n} + a_{0} = y_{n}$$

for the n + 1 coefficients.

2. Newton Form Method. Set

$$P(x) = c_0 + c_1(x - x_0) + c_2(x - x_0)(x - x_1) + \dots + c_n(x - x_0)(x - x_1) \cdots (x - x_{n-1})$$

and use the following recursive formulae to determine the coefficients c_k :

$$c_{k} = \frac{y_{k} - P_{k-1}(x_{k})}{(x_{k} - x_{0})(x_{k} - x_{1})\cdots(x_{k} - x_{k-1})}$$

$$P_{k}(x) = P_{k-1}(x) + c_{k}(x - x_{0})(x - x_{1})\cdots(x - x_{k-1})$$

3. Lagrange Form Method. For k = 0, 1, ..., n compute the cardinal functions

$$\ell_k(x) = \prod_{\substack{j=0\\j\neq k}}^n \frac{(x-x_j)}{(x_k-x_j)} = \frac{(x-x_0)(x-x_1)\cdots(x-x_{k-1})(x-x_{k+1})\cdots(x-x_n)}{(x_k-x_0)(x_k-x_1)\cdots(x_k-x_{k-1})(x_k-x_{k+1})\cdots(x_k-x_n)}$$

and then set

$$P(x) = \sum_{k=0}^{n} y_k \ell_k(x)$$

There is one more method that is, computationally, much more efficient than any of the algorithms above. This is the so-called method of **divided differences**.

NOTATION 17.1. Let $\{(x_i, y_i) \mid i = 0, ..., n\}$ be an ordered set of n + 1 data points, let $x_k, x_{k+1}, ..., x_{k+j}$ be any set of j consecutive nodes and let

$$\mathcal{P}_{k}(x) = c_{k,0} + c_{k,1} \left(x - x_{k} \right) + c_{k,2} \left(x - x_{k} \right) \left(x - x_{k+1} \right) + \dots + c_{k,j} \left(x - x_{k} \right) \left(x - x_{k+1} \right) \cdots \left(x - x_{k+j-2} \right) \left(x - x_{k+j-1} \right) = c_{k,0} + c_{k,1} \left(x - x_{k} \right) + c_{k,2} \left(x - x_{k} \right) \left(x - x_{k+1} \right) + \dots + c_{k,j} \left(x - x_{k} \right) \left(x - x_{k+1} \right) \cdots \left(x - x_{k+j-2} \right) \left(x - x_{k+j-1} \right) = c_{k,0} + c_{k,1} \left(x - x_{k} \right) + c_{k,2} \left(x - x_{k} \right) \left(x - x_{k+j-1} \right) = c_{k,0} + c_{k,1} \left(x - x_{k} \right) + c_{k,2} \left(x - x_{k} \right) \left(x - x_{k+j-1} \right) = c_{k,0} + c_{k,1} \left(x - x_{k} \right) + c_{k,2} \left(x - x_{k} \right) = c_{k,0} + c_{k,1} \left(x - x_{k} \right) + c_{k,2} \left(x - x_{k} \right) + c_{k,2} \left(x - x_{k} \right) = c_{k,0} + c_{k,1} \left(x - x_{k} \right) + c_{k,2} \left(x - x_{k} \right) + c_{k,2} \left(x - x_{k} \right) = c_{k,0} + c_{k,1} \left(x - x_{k} \right) + c_{k,2} \left(x - x_{k} \right) + c_{k,2} \left(x - x_{k} \right) = c_{k,1} \left(x - x_{k} \right) + c_{k,2} \left(x - x_{k} \right) + c_{k$$

be the Newton form of the interpolation polynomial for $\{(x_i, y_j) \mid i = k, \dots, k+j\}$. The **divided difference**

$$f[x_k, x_{k+1}, \ldots, x_{k+j}]$$

is the highest order coefficient $c_{k,j}$ of $\mathcal{P}_k(x)$.

REMARK 17.2. Note that if we set k = 0 then the divided differences $f[x_0, x_1, x_j]$ are just the coefficients c_j appearing in the Newton of the interpolation polynomial for $\{(x_i, y_i) \mid i = 0, ..., n\}$. For in this case, the polynomials

$$P_j(x) = P_{j-1}(x) + c_j (x - x_0) (x - x_1) \cdots (x - x_{j-1})$$

 and

$$\mathcal{P}_{0}(x) = c_{k,0} + c_{k,1} \left(x - x_{0}
ight) + c_{k,2} \left(x - x_{0}
ight) \left(x - x_{1}
ight)$$

$$\begin{aligned} \mathcal{P}_{0}(x) &= c_{k,0} + c_{k,1} \left(x - x_{0} \right) + c_{k,2} \left(x - x_{0} \right) \left(x - x_{1} \right) + \cdots \\ &\cdots + c_{0,j} \left(x - x_{0} \right) \cdots \left(x - x_{j-1} \right) + \cdots + c_{0,n} \left(x - x_{0} \right) \cdots \left(x - x_{n-1} \right) \\ &= f[x_{0}] + f[x_{0}, x_{1}] \left(x - x_{0} \right) + f[x_{0}, x_{1}, x_{2}] \left(x - x_{0} \right) \left(x - x_{1} \right) + \cdots \\ &\cdots + f[x_{0}, x_{1}, \dots, x_{j}] \left(x - x_{0} \right) \cdots \left(x - x_{j-1} \right) + \cdots \\ &\cdots + f[x_{0}, x_{1}, \dots, x_{n}] \left(x - x_{0} \right) \cdots \left(x - x_{n-1} \right) \\ &= c_{0} + c_{1} (x - x_{0}) + c_{2k,2} \left(x - x_{0} \right) \left(x - x_{1} \right) + \cdots \\ &\cdots + c_{j} \left(x - x_{0} \right) \cdots \left(x - x_{j-1} \right) + \cdots \\ &\cdots + c_{n} \left(x - x_{0} \right) \cdots \left(x - x_{n-1} \right) \end{aligned}$$

THEOREM 17.3. The divided differences satisfy the following recursion relations

$$f[x_i, x_{i+1}, \dots, x_{i+j}] = \frac{f[x_{i+1}, x_{i+1}, \dots, x_{i+j}] - f[x_i, x_{i+1}, \dots, x_{i+j-1}]}{x_{i+j} - x_i}$$

Proof. It suffices to prove this for i = 0 and j = n: because for any other choice of i or j, we can always construct a new set of data $\{(\tilde{x}_k, \tilde{y}_k) = (x_{i+k}, y_{i+k}) \mid k = 0, 1, \dots, \tilde{n} = j\}$ for which the relation

$$f[\tilde{x}_{0}, \tilde{x}_{1}, \dots, \tilde{x}_{\tilde{n}}] = \frac{f[\tilde{x}_{1}, \dots, \tilde{x}_{n}] - f[\tilde{x}_{1}, \dots, \tilde{x}_{\tilde{n}-1}]}{\tilde{x}_{\tilde{n}} - \tilde{x}_{0}}$$

is equivalent to the relation in the problem statement. Let $P_{n-1}(x)$ be the polynomial of degree $\leq n-1$ that interpolates the data at the first *n* data points $\{(x_0, y_0), \ldots, (x_{n-1}, y_{n-1})\}$ and let $Q_{n-1}(x)$ be the polynomial that interpolates the data at the last *n* data points $\{(x_1, y_1), \ldots, (x_n, y_n)\}$. Then if we set

$$Q(x) = Q_{n-1}(x) + \frac{x - x_n}{x_n - x_0} \left(Q_{n-1}(x) - P_{n-1}(x) \right)$$

then

$$Q(x_i) = \begin{cases} Q_{n-1}(x_0) + \frac{x_0 - x_n}{x_n - x_0} \left(Q_{n-1}(x) - P_{n-1}(x) \right) = P_{n-1}(x_0) = y_0 &, & \text{if } i = 0 \\ Q_{n-1}(x_i) + \frac{x_1 - x_n}{x_n - x_0} \left(Q_{n-1}(x_i) - P_{n-1}(x_i) \right) = y_i - \frac{x_i - x_n}{x_n - x_0} (0) = y_i &, & \text{if } 0 < i < n \\ Q_{n-1}(x_n) + \frac{x_n - x_n}{x_n - x_0} \left(Q_{n-1}(x_n) - P_{n-1}(x_n) \right) = y_n &, & \text{if } i = n \end{cases}$$

Therefore, Q(x) is the interpolation polynomial P(x) for the data $\{(x_i, y_i) \mid i = 0, ..., n\}$. Now the coefficient of the highest power of x for P(x) is

$$P(x) \approx f[x_0, \ldots, x_n](x - x_0) \cdots (x - x_n) \approx f[x_0, \ldots, x_n]x^n + \mathcal{O}(x^{n-1})$$

while the coefficient of the highest power of x for Q(x) will be

$$Q(x) \approx \frac{x - x_n}{x_n - x_0} \left(\left(f\left[x_1, \dots, x_n\right] (x - x_1) \cdots (x - x_n) - f\left[x_0, \dots, x_{n-1}\right] (x - x_0) \cdots (x - x_{n-1}) \right) + O\left(x^{n-1}\right) \right) \\ \approx \left(\frac{f\left[x_1, \dots, x_n\right]}{x_n - x_0} - \frac{f\left[x_0, \dots, x_{n-1}\right]}{x_n - x_0} \right) x^n - \mathcal{O}\left(x^{n-1}\right) \right)$$

Since the highest order coefficients must agree we have

$$f[x_0, \dots, x_n] = \frac{f[x_1, \dots, x_n] - f[x_0, \dots, x_{n-1}]}{x_n - x_0}$$

Now consider how we might construct the interpolation polynomial using divided differences. Suppose P(x) is the interpolation polynomial for a problem with four data points x_0, x_1, x_2, x_3 . We then have

$$P(x) = c_0 + c_1(x - x_0) + c_2(x - x_0)(x - x_1) + c_3(x - x_0)(x - x_1)(x - x_2) = f[x_0] + f[x_0, x_1](x - x_0) + f[x_0, x_1, x_2](x - x_0)(x - x_1) + f[x_0, x_1, x_2, x_3](x - x_0)(x - x_1)(x - x_2)$$

Now according to the preceding theorem

$$\begin{split} f[x_0, x_1, x_2, x_3] &= \frac{f[x_1, x_2, x_3] - f[x_0, x_1, x_2]}{x_3 - x_0} \\ &= \frac{1}{x_3 - x_0} \left(\frac{f[x_2, x_3] - f[x_1, x_2]]}{x_3 - x_1} - \frac{f[x_1, x_2] - f[x_0, x_1]}{x_1 - x_0} \right) \\ &= \frac{1}{(x_3 - x_0)(x_3 - x_1)} \left(\frac{f[x_3] - f[x_2]}{x_3 - x_2} - \frac{f[x_2] - f[x_1]}{x_2 - x_1} \right) \\ &- \frac{1}{(x_3 - x_0)(x_1 - x_0)} \left(\frac{f[x_2] - f[x_1]}{x_2 - x_1} - \frac{f[x_1] - f[x_0]}{x_1 - x_0} \right) \\ &= \frac{1}{(x_3 - x_0)(x_3 - x_1)} \left(\frac{y_3 - y_2}{x_3 - x_2} - \frac{y_2 - y_1}{x_2 - x_1} \right) \\ &- \frac{1}{(x_3 - x_0)(x_1 - x_0)} \left(\frac{y_2 - y_1}{x_2 - x_1} - \frac{y_1 - y_0}{x_1 - x_0} \right) \end{split}$$

However, this is not how we'll want to compute divided differences (by breaking down the complicated $f[x_0, \ldots, x_i]$ to the original data). Rather, we'll employ a bottoms up approach. For notational and calculational convenience, we'll set

$$F[[i, 0] \equiv f[x_i] = y_i$$

$$F[i, j] \equiv f[x_i, x_{i+1}, \dots, x_{i+j}]$$

so that our recursion relations

$$f[x_i, x_{i+1}, \dots, x_{i+j}] = \frac{f[x_{i+1}, \dots, x_{i+j}] - f[x_i, \dots, x_{i+j-1}]}{x_{i+j} - x_i}$$

can be expressed a bit more succinctly as

$$F[i, j] = \frac{F[i+1, j-1] - F[i, j-1]}{x_{i+j} - x_i}$$

 \bullet Step 1. Set

$$F[i,0] = y_i \quad , \quad i = 0, \dots, n$$

• Step 2. Set

$$F[i,1] = \frac{F[i+1,0] - F[i,0]}{x_{i+1} - x_i} \quad , \quad i = 0, \dots, n-1$$

• Step 3. Set

$$F[i,2] := \frac{f[i+1,1] - f[i,1]}{x_{i+2} - x_i}$$
, $i = 0, \dots, n-2$

- :
- Step n 1. Set

$$f[i, \dots, n-1] := \frac{f[i+1, n-2] - f[i, n-2]}{x_n - x_0}$$
, $i = 0, 1$

• Step n. Set

$$F[0, n] := \frac{F[1, n-1] - F[0, n-1]}{x_n - x_0} \quad .$$

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• For each i from 0 to n, set

$$c_i = F[0, i] \equiv f[x_0, x_1, \dots, x_i]$$

• The Newton form of the interpolation polynomial will then be

$$P(x) = \sum_{i=0}^{n} c_i \left(\prod_{j=0}^{i-1} (x - x_j) \right)$$

The following Maple code implements this algorithm.

```
#initialize array F[i,0]
for i from 0 to n do
  F[i,0] := Y[i];
od:
#apply recursion relations
for j from 1 to n do
  for i from 0 to n-j do
      F[i,j] := (F[i+1,j-1] - F[i,j-1])/(X[i+j] - X[i]);
   od:
od:
#construct Newton form of interpolation polynomial
p := F[0,0]; # = Y[0];
g := 1
for i from 1 to n do
    g := (x-X[i-1])*g
 p := p + F[0,i]*g;
od:
#identify the total coefficient of each power of x
for i from 0 to n do
  c := coeff(p, x, i):
   c := evalf(c,3):
   lprint('coefficient of x to the',i,'is',c):
od:
```

Suppose we implement this code on a test function like

$$T(x) = 2x^8 - 10x^5 - 20x - 50 \quad ,$$

setting up our data points in the following simple-minded way

$$x_i = a + \frac{b-a}{n}i$$

$$y_i = T(x_i)$$

for various choices of n, and intervals [a, b]. Surprisingly, we don't get consistent results. For example, for n = 10, [a, b] = [-10, 10], we obtain

$$P(x) = (0.0)x^{1}0 + (0.0)x^{9} + (2.0)x^{8} + (0.0)x^{7} + (0.0)x^{6} - (10.0)x^{5} + (0.0)x^{4} + (0.0)x^{3} + (0.0)x^{2} + (6.0 \times 10^{5})x + (1.0 \times 10^{1})$$

On the other hand, taking n = 10, [a, b] = [-0.005, 0.005], we obtain

$$P(x) = -(2.8 \times 10^5)x^{10} + (-1.4 \times 10^5)x^9 + (827)x^8 + (41.3)x^7 - (7.52)x^6 - (10.0)x^5 + (2.3 \times 10^{-4})x^4 + (1.1 \times 10^{-5})x^3 + (1.6 \times 10^{-8})x^2 - (20.0)x - (50.0)$$

Of course, such discrepancies can be traced to the floating point errors in the numerical algorithm. The way to get around such inconsistencies is to take a three step approach.

- Carry out an interpolation in a region [a, b] where the data is changing very rapidly to get a handle on the higher degree terms of P(x).
- Carry out an interpolation in a region [a, b] where the rate at which data is changing rather moderately to get a handle on the lower degree terms of P(x).
- Look for a region where the high degree terms and the low degree terms have about the same influence to get a final interpolation for P(x).

Note, however, that the test regions described above need not be near the origin, nor can there sizes be predicted *a priori*. Consider, for example, what might be appropriate regions for interpolating the following polynomial

$$T(x) = 10^{-6} \left[\left(x - 500 \right)^5 - x + 500 \right]$$