LECTURE 11

Linear Transformations and Matrices

1. Matrix Multiplication

We have put this off long enough; let us now define matrix multiplication.

Let $Mat_{n,m}(\mathbb{F})$ be the set of $n \times m$ matrices with entries in \mathbb{F} . As usual, we will write a typical element of $Mat_{n,m}(\mathbb{F})$ as an array with n rows and m columns

$$\mathbf{A} = \left(\begin{array}{ccc} a_{11} & \cdots & a_{1m} \\ \vdots & \ddots & \vdots \\ a_{n1} & \cdots & a_{nm} \end{array}\right)$$

DEFINITION 11.1. Let $\mathbf{A} \in Mat_{n,m}(\mathbb{F})$ and let $\mathbf{B} \in Mat_{m,\ell}(\mathbb{F})$. The matrix product \mathbf{AB} is defined as the matrix in $Mat_{n,\ell}(\mathbb{F})$ with entries

$$(\mathbf{AB})_{ij} = \sum_{k=1}^{m} a_{ik} b_{kj} \qquad , \qquad 1 \le i \le n \quad , \quad 1 \le j \le \ell$$

REMARK 11.2. Another formulation of the rule for matrix multiplication is this: the $(ij)^{th}$ element of the matrix product **AB** is the dot product for the i^{th} row vector of **A** with the j^{th} column vector of **B**.

Recall that the set $Mat_{n,m}(\mathbb{F})$ is naturally a vector space over \mathbb{F} with scalar multiplication and vector addition defined by

$$\begin{aligned} &(\lambda \cdot \mathbf{A})_{ij} &= \lambda a_{ij} \qquad , \qquad 1 \leq i \leq n \quad , \quad 1 \leq j \leq m \\ &(\mathbf{A} + \mathbf{B})_{ij} &= a_{ij} + b_{ij} \qquad , \qquad 1 \leq i \leq n \quad , \quad 1 \leq j \leq m \end{aligned}$$

THEOREM 11.3. Let $\mathbf{A}, \mathbf{C} \in Mat_{n,m}(\mathbb{F}), \mathbf{B}, \mathbf{D} \in Mat_{m,\ell}(\mathbb{F})$ and let $\alpha, \beta \in \mathbb{F}$.

•
$$\mathbf{A} (\alpha \mathbf{B} + \beta \mathbf{D}) = \alpha (\mathbf{A}\mathbf{B}) + \beta (\mathbf{A}\mathbf{D})$$

• $(\alpha \mathbf{A} + \beta \mathbf{C}) \mathbf{B} = \alpha (\mathbf{A}\mathbf{B}) + \beta (\mathbf{C}\mathbf{B})$

• $(\alpha \mathbf{A} + \beta \mathbf{C}) \mathbf{B} = \alpha (\mathbf{AB}) + \beta (\mathbf{CB})$

COROLLARY 11.4. Let **A** be an $n \times m$ matrix. Then for each $\ell = 1, 2, 3, \ldots$, **A** defines a family of linear transformations $L_{\ell} : Mat_{m,\ell}(\mathbb{F}) \to Mat_{n,\ell}(\mathbb{F})$ via left multiplication

$$Mat_{m,\ell}\left(\mathbb{F}\right) \ni \mathbf{B} \quad \longmapsto \quad \mathbf{AB} \in Mat_{n,\ell}\left(\mathbb{F}\right)$$

and for each $k = 1, 2, 3, ..., \mathbf{A}$ defines a family of linear transformations $R_k : Mat_{k,n}(\mathbb{F}) \to Mat_{k,m}(\mathbb{F})$ via right multiplication

$$Mat_{k,n}\left(\mathbb{F}\right) \ni \mathbf{B} \quad \longmapsto \quad \mathbf{BA} \in Mat_{k.m}\left(\mathbb{F}\right)$$

REMARK 11.5. Because we can think of a vectors in \mathbb{F}^m either as $m \times 1$ matrices (column vectors) or as $1 \times m$ matrices (row vectors), we actually have two possibilities for implementing matrix multiplication on \mathbb{F}^m . This ambiguity is usually resolved by *adopting the convention* that elements of \mathbb{F}^m correspond to $m \times 1$ matrices.

2. Linear Transformations, Bases, and Matrix Multiplication

Let V and W be finitely generated vector spaces and let $T: V \to W$ be a linear transformation from V to W. Since V and W are finitely generated vector spaces they both have bases. Let $B = \{v_1, \ldots, v_m\}$ be a basis for V and let $B' = \{w_1, \ldots, w_n\}$ be a basis for W. From the data T, B, and B' we can form a matrix in $Mat_{\mathbb{F}}(n,m)$; for each basis vector $v_i \in V$ gets mapped by T to a vector $T(v_i) \in W$, which in turn must be expressible in terms of the basis B' of W. Say

$$T(v_i) = \lambda_1^{(i)} w_1 + \lambda_2^{(i)} w_2 + \dots + \lambda_n^{(i)} w_n$$

Then a more general vector $v = a_1v_1 + \cdots + a_mv_m$ gets mapped to

$$T(v) = T(a_{1}v_{1} + \dots + a_{m}v_{m})$$

$$= a_{1}T(v_{1}) + \dots + a_{m}T(v_{m}) \qquad \text{because } T \text{ is a linear transformation}$$

$$= a_{1}\lambda_{1}^{(1)}w_{1} + \dots + a_{1}\lambda_{n}^{(1)}w_{n}$$

$$+ a_{2}\lambda_{1}^{(2)}w_{1} + \dots + a_{2}\lambda_{n}^{(2)}w_{n}$$

$$+ \dots$$

$$+ a_{m}\lambda_{1}^{(m)}w_{1} + \dots + a_{m}\lambda_{n}^{(m)}w_{n}$$

$$= \left(\lambda_{1}^{(1)}a_{1} + \lambda_{1}^{(2)}a_{2} + \dots + \lambda_{1}^{(m)}a_{m}\right)w_{1}$$

$$+ \left(\lambda_{2}^{(1)}a_{1} + \lambda_{2}^{(2)}a_{2} + \dots + \lambda_{2}^{(m)}a_{m}\right)w_{2}$$

$$+ \dots$$

$$+ \left(\lambda_{n}^{(1)}a_{1} + \lambda_{n}^{(2)}a_{2} + \dots + \lambda_{n}^{(m)}a_{m}\right)w_{n}$$

Put another way, a vector $v \in V$ with coordinate vector $[a_1, \ldots, a_m] \in \mathbb{F}^m$ with respect to the basis $B \subset V$ gets mapped to T(v) which has coordinate vector

$$\left[\lambda_1^{(1)}a_1 + \lambda_1^{(2)}a_2 + \dots + \lambda_1^{(m)}a_m, \lambda_1^{(1)}a_2 + \lambda_2^{(2)}a_2 + \dots + \lambda_2^{(m)}a_m, \dots, \lambda_n^{(1)}a_1 + \lambda_n^{(2)}a_2 + \dots + \lambda_n^{(m)}a_m\right]$$

with respect to the basis $B' = \{w_1, \ldots, w_n\}$ of W. Let us now write the coordinate vector $[a_1, \ldots, a_m]$ as a $m \times 1$ matrix, and coordinate vector of T(v) as an $n \times 1$ matrix. Then we have

$$(1) \quad \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_m \end{bmatrix} \xrightarrow{T} \quad \begin{bmatrix} \lambda_1^{(1)}a_1 + \lambda_1^{(2)}a_2 + \dots + \lambda_1^{(m)}a_m \\ \lambda_1^{(1)}a_2 + \lambda_2^{(2)}a_2 + \dots + \lambda_2^{(m)}a_m \\ \vdots \\ \lambda_n^{(1)}a_1 + \lambda_n^{(2)}a_2 + \dots + \lambda_n^{(m)}a_m \end{bmatrix} = \begin{bmatrix} \lambda_1^{(1)} & \lambda_1^{(2)} & \dots & \lambda_1^{(m)} \\ \lambda_2^{(1)} & \lambda_2^{(2)} & \dots & \lambda_2^{(m)} \\ \vdots & \vdots & \ddots & \vdots \\ \lambda_n^{(1)} & \lambda_n^{(2)} & \dots & \lambda_n^{(m)} \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_m \end{bmatrix}$$

where on the right we have simply recognized that the coordinate vector for T(v) can also be obtained via a matrix multiplication.

Let me summarize this result. Let $B = \{v_1, \ldots, v_m\}$ be a basis for V, let $B' = \{w_1, \ldots, w_n\}$ be a basis for W, and let $T: V \to W$ be a linear transformation. Form an $n \times m$ matrix $\mathbf{T}_{B,B'}$ by utilizing the coordinate vectors for $T(v_i)$ with respect to B' as columns. Then a vector $v \in V$ with coordinate vector $\mathbf{v}_B \in \mathbb{F}^m$ with respect to B gets mapped by T to the vector in W with coordinate vector $\mathbf{T}_{B,B'}\mathbf{v}_B$.

The upshot of this is: once you coordinatize your vector spaces, a linear transformation is always implementable by matrix multiplication.

3. The Kernel and Image of a Linear Transformation

Given a linear transformation $T: V \to W$, we have two associated subspaces of, respectively, the domain V and the codomain W:

$$\ker (T) = \{ \mathbf{v} \in V \mid T(\mathbf{v}) = \mathbf{0}_W \}$$

range (T) = $\{ \mathbf{w} \in W \mid \mathbf{w} = T(\mathbf{v}) \text{ for some } \mathbf{v} \in V \}$

How does one compute these subspaces? Well, as is typical of abstract vector spaces, there little we can calculate without first positing some bases. So let $B = \{\mathbf{v}_1, \ldots, \mathbf{v}_m\}$ be a basis for V and let B' = $\{\mathbf{w}_1,\ldots,\mathbf{w}_n\}$ be a basis for W. As we say in the preceding section, a linear transformation $T: V \to W$ is equivalent to defining a certain matrix multiplication that sends coordinate vectors for V to coordinate vectors for W. Schematically, the way this works is

$$\mathbf{v} \in V \qquad \underbrace{T} \qquad T(v) \in W$$
$$\xrightarrow{\mathcal{N}} \qquad \underbrace{\mathbf{T}}_{BB'} \qquad \underbrace{\mathbf{T}}_{BB'} \mathbf{v}_B \in \mathbb{F}^n$$

where $\mathbf{T}_{BB'}$ is the $n \times m$ matrix formed by using the coordinate vectors (w.r.t. B') of each $T(v_i)$ as columns.

Because of the tight one-to-one correspondence between vectors and their coordinate vectors, we should be able to identify ker (T) with a certain subspace of \mathbb{F}^m and range(T) with a certain subspace of \mathbb{F}^n . Indeed,

$$T(v) = 0 \quad \iff \quad \mathbf{T}_{BB'} \mathbf{v}_B = \mathbf{0}_{\mathbb{F}^n}$$

which tells us that

(2)
$$\ker(T) \iff NullSp(\mathbf{T}_{BB'}) \equiv \text{solution set of } \mathbf{T}_{BB'}\mathbf{x} = \mathbf{0}$$

Also, if we denote the components of \mathbf{v}_B as $[a_1, \ldots, a_m]$ and the columns of $\mathbf{T}_{BB'}$ as $\mathbf{c}_1, \ldots, \mathbf{c}_m$ (still with $\mathbf{c}_i = \text{coordinate vector for } T(v_i) \text{ with respect to } B'), \text{ then } \mathbf{v}_B = [a_1]$

$$\mathbf{T}_{BB'}\mathbf{v}_B = a_1\mathbf{c}_1 + a_2\mathbf{c}_2 + \dots + a_m\mathbf{c}_m$$

Thus, as we let \mathbf{v}_B vary over \mathbb{F}^m , the vectors $\mathbf{T}_{BB'}\mathbf{v}_B$ run over the span of the columns of $\mathbf{T}_{BB'}$; and so

(3)
$$range(T) \iff ColSp(\mathbf{T}_{BB'})$$

Let's restate this result as a theorem:

THEOREM 11.6. Suppose V and W are finitely generated vector spaces and $T: V \to W$ is a linear transformation. Let $B = \{b_1, \ldots, b_m\}$ be a basis for V and let $B' = \{b'_1, \ldots, b'_n\}$ be a basis for W. Let $i_B : V \to \mathbb{F}^m$ and $i_{B'} = W \to \mathbb{F}^n$ be the associated coordinatization isomorphisms. Finally, let $\mathbf{A}_{T,B,B'}$ be associated $n \times m$ matrix of whose columns are given by

$$\mathbf{c}_{i} = i_{B'} \left(T \left(b_{i} \right) \right) \in \mathbb{F}^{n} \quad , \quad i = 1, \dots, m$$

Then

- (i) The linear transformation $i_{B'} \circ T \circ i_B^{-1} : \mathbb{F}^m \to \mathbb{F}^n$ coincides with matrix multiplication by $\mathbf{A}_{T,B,B'}$. (ii) ker $(T) = i_B^{-1} (NullSp(\mathbf{A}_{T,B,B'}))$, where $NullSp(\mathbf{A}_{T,B,B'}) \equiv$ the solution set of $\mathbf{A}_{T,B,B'}\mathbf{x} = \mathbf{0}$ in
- (iii) Im $(T) = i_B^{-1} (ColSp(\mathbf{A}_{T,B,B'})) = span (T(b_1), \dots, T(b_m)).$

In addition, we also have

COROLLARY 11.7. If $T: V \to W$ is a linear transformation between finitely generated vector spaces, then

 $\dim (V) = \ker (T) + \dim \operatorname{Im} (T)$

Proof. From the theorem,

$$\ker\left(T\right) = i_{B}^{-1}\left(NullSp\left(\mathbf{A}_{T,B,B'}\right)\right)$$

Since i_B is an isomorphism, ker (T) and the solution set of $\mathbf{A}_{T,B'B'}\mathbf{x} = \mathbf{0}$ must have the same dimension. On the other, by the theorem we also have that Im(T) is isomorphic to $ColSp(\mathbf{A}_{T,B,B'})$ and so Im(T) must have the same dimension as the column space of $\mathbf{A}_{T,B,B'}$. In other words, dim $(\text{Im}(T)) = rank(\mathbf{A}_{T,B,B'})$. But now from Corollary 8.4 of Lecture 8 we know

(4) dim (solution set of
$$\mathbf{A}_{T,B,B'}\mathbf{x} = \mathbf{0}$$
) = # columns of $\mathbf{A}_{T,B,B} - rank(\mathbf{A}_{T,B,B'})$

Using

columns of
$$\mathbf{A}_{T,B,B'} = \#$$
 basis vectors in $B = \dim V$
 $rank(\mathbf{A}_{T,B,B'}) = \dim (ColSp(\mathbf{A}_{T,B,B'})) = \dim \operatorname{Im}(T)$
dim (solution set of $\mathbf{A}_{T,B,B'}\mathbf{x} = \mathbf{0}$) = dim (ker (T))

We get from (4)

 $\dim \left(\ker \left(T \right) \right) = \dim V - \dim \left(\operatorname{Im} \left(T \right) \right)$

and the statement of the corollary follows.

EXAMPLE 11.8. Find the kernel and image of the following linear transformation acting on polynomials of degree ≤ 3

$$T\left(p\right) = x\frac{dp}{dx} - 2p$$

Using the standard basis $B = \{x^3, x^2, x, 1\}$ for the vector space of polynomial of degree 3 we see

$$x^{3} \xrightarrow{T} \left(x\frac{d}{dx}-2\right)x^{3} = 3x^{3}-2x^{3}=x_{3} \rightarrow [1,0,0,0]$$

$$x^{2} \xrightarrow{T} \left(x\frac{d}{dx}-2\right)x^{2} = 2x^{2}-2x^{2}=0 \rightarrow [0,0,0,0]$$

$$x \xrightarrow{T} \left(x\frac{d}{dx}-2\right)x = x-2x=-x \rightarrow [0,0,-1,0]$$

$$1 \xrightarrow{T} \left(x\frac{d}{dx}-2\right)x = 0-2=-2 \rightarrow [0,0,0,-2]$$

and so

$$\mathbf{T}_{BB} = \left(\begin{array}{rrrr} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -2 \end{array} \right)$$

From this is fairly obvious that

$$NullSp(\mathbf{T}_{BB}) = span \begin{pmatrix} 0\\1\\0\\0 \end{pmatrix} \longleftrightarrow span (x^{2})$$
$$ColSp(\mathbf{T}_{BB}) = span \begin{pmatrix} \begin{bmatrix} 1\\0\\0\\0\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\1\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\1\\0 \end{bmatrix}, \begin{bmatrix} 0\\0\\1\\0 \end{bmatrix} \end{pmatrix} \longleftrightarrow span (x^{3}, x, 1)$$

and so

$$\ker (T) = span (x^2)$$

range (T) = span (x³, x, 1)