

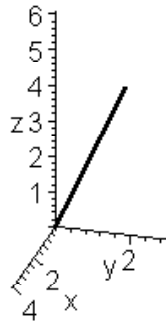
**Math 4013**  
**Solutions to Homework Problems for Chapter 1**

1. Let  $\mathbf{v} = 3\mathbf{i} + 4\mathbf{j} + 5\mathbf{k}$  and  $\mathbf{w} = \mathbf{i} - \mathbf{j} + \mathbf{k}$ . Compute  $\mathbf{v} + \mathbf{w}$ ,  $3\mathbf{v}$ ,  $6\mathbf{v} + 8\mathbf{w}$ ,  $-2\mathbf{v}$ ,  $\mathbf{v} \cdot \mathbf{w}$ ,  $\mathbf{v} \times \mathbf{w}$ . Interpret each geometrically by graphing the vectors.

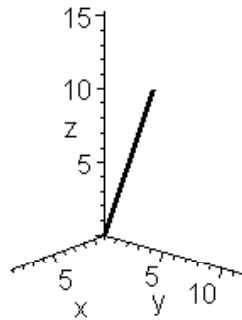
$$\mathbf{v} = (3, 4, 5)$$

$$\mathbf{w} = (1, -1, 1)$$

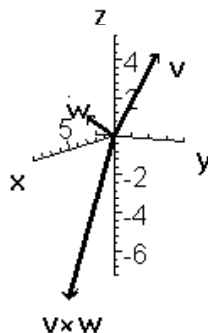
- $\mathbf{v} + \mathbf{w} = (3 + 1, 4 + (-1), 5 + 1) = (4, 3, 6)$



- $3\mathbf{v} = (9, 12, 15)$



- $6\mathbf{v} + 8\mathbf{w} = (18, 24, 30) + (8, -8, 8) = (26, 16, 38)$
- $-2\mathbf{v} = (-6, -8, -10)$
- $\mathbf{v} \cdot \mathbf{w} = (3)(1) + (4)(-1) + (5)(1) = 3 - 4 + 5 = 4$
- $\mathbf{v} \times \mathbf{w} = ((4)(1) - (5)(-1), (5)(1) - (3)(1), (3)(-1) - (4)(1)) = (9, 2, -7)$



□

2.

(a) Find the equation of the line through  $(-1, 2, -1)$  in the direction of  $\mathbf{j}$ .

- An Equation of a Line has the form

$$\mathbf{r}(t) = \mathbf{r}_o + t\mathbf{v}$$

where  $\mathbf{r}_o$  is the position vector of a point on the line and  $\mathbf{v}$  is a vector representing the direction of the line. We thus have, for the case at hand,

$$\mathbf{r}(t) = (-1, 2, -1) + t(0, 1, 0) = (-1, 2 + t, -1) \quad .$$

□

(b) Find the equation of the line passing through  $(0, 2, -1)$  and  $(-3, 1, 0)$ .

- The line through  $\mathbf{a} = (0, 2, -1)$  and  $\mathbf{b} = (-3, 1, 0)$ , definitely passes through the point  $\mathbf{a}$  and has the same direction as  $\mathbf{b} - \mathbf{a}$ . Thus, its equation is

$$\mathbf{r}(t) = \mathbf{a} + t(\mathbf{b} - \mathbf{a}) = (0, 2, -1) + t(-3, -1, 1) = (-3t, 2 - t, -1 + t) \quad .$$

□

(c) Find the equation for the plane perpendicular to  $(-2, 1, 2)$  and passing through  $(-1, 1, 3)$ .

- Let  $\mathbf{r} = (x, y, z)$  be a point in the plane. Then the line through  $\mathbf{r}$  and  $\mathbf{r}_o = (1, 1, 1)$  must lie entirely in the plane; and so must be perpendicular to the normal vector to the plane,  $\mathbf{n} = (-1, 1, -1)$ . This leads to the condition

$$\begin{aligned} 0 &= \mathbf{n} \cdot (\mathbf{r} - \mathbf{r}_o) \\ &= (-1, 1, -1) \cdot (x - 1, y - 1, z - 1) \\ &= -x + 1 + y - 1 - z + 1 \\ &= -x + y - z + 1 \end{aligned}$$

or

$$x - y + z = 1 \quad .$$

The last equation is the equation of the plane.

□

3. Compute  $\mathbf{v} \cdot \mathbf{w}$  for the following sets of vectors.(a)  $\mathbf{v} = -\mathbf{i} + \mathbf{j} = (-1, 1, 0)$ ;  $\mathbf{w} = \mathbf{k} = (0, 0, 1)$ .(b)  $\mathbf{v} = \mathbf{i} + 2\mathbf{j} - \mathbf{k} = (1, 2, -1)$ ;  $\mathbf{w} = 3\mathbf{i} + \mathbf{j} = (3, 1, 0)$ .(c)  $\mathbf{v} = -2\mathbf{i} - \mathbf{j} + \mathbf{k} = (-2, -1, 1)$ ;  $\mathbf{w} = 3\mathbf{i} + 2\mathbf{j} - 2\mathbf{k} = (3, 2, -2)$ .

- Using the formula

$$\mathbf{v} \cdot \mathbf{w} = v_1w_1 + v_2w_2 + v_3w_3$$

we find

(a)

$$\mathbf{v} \cdot \mathbf{w} = (-1)(0) + (1)(0) + (0)(1) = 0$$

(b)

$$\mathbf{v} \cdot \mathbf{w} = (-1)(3) + (2)(1) + (-1)(0) = -1$$

(c)

$$\mathbf{v} \cdot \mathbf{w} = (-2)(3) + (-1)(2) + (1)(-2) = -10$$

□

4. Compute  $\mathbf{v} \times \mathbf{w}$  for the vectors in Exercise 3.

- Using the formula

$$\mathbf{v} \times \mathbf{w} = (v_2 w_3 - v_3 w_2, v_3 w_1 - v_1 w_3, v_1 w_2 - v_2 w_1)$$

we find

(a)

$$\mathbf{v} \times \mathbf{w} = ((1)(1) - (0)(0), (0)(0) - (-1)(1), (-1)(0) - (1)(0)) = (1, 1, 0)$$

(b)

$$\mathbf{v} \times \mathbf{w} = ((2)(0) - (-1)(1), (-1)(3) - (1)(0), (1)(1) - (2)(3)) = (1, -3, -5)$$

(c)

$$\mathbf{v} \times \mathbf{w} = ((-1)(-2) - (1)(3), (1)(3) - (-2)(-2), (-2)(2) - (-1)(3)) = (-1, -1, -1)$$

□

5. Convert the point  $(0, 3, 4)$  from Cartesian to cylindrical and spherical coordinates.

- The relationship between Cartesian and cylindrical coordinates is given by

$$\begin{aligned} x &= r \cos \theta & r &= \sqrt{x^2 + y^2} \\ y &= r \sin \theta & \theta &= \tan^{-1} \left( \frac{y}{x} \right) \\ z &= z & z &= z \end{aligned}$$

and the relationship between Cartesian and spherical coordinates is given by

$$\begin{aligned} x &= \rho \cos \theta \sin \phi & \rho &= \sqrt{x^2 + y^2 + z^2} \\ y &= \rho \sin \theta \sin \phi & \theta &= \tan^{-1} \left( \frac{y}{x} \right) \\ z &= \rho \cos \phi & \phi &= \cos^{-1} \left( \frac{z}{\rho} \right) \end{aligned}$$

We thus have

$$\begin{aligned} r &= \sqrt{0^2 + 3^2} = 3 \\ \theta &= \tan^{-1} \left( \frac{3}{0} \right) = \tan^{-1} (+\infty) = \frac{\pi}{2} \\ z &= 4 \end{aligned}$$

for the polar coordinates of the point  $(0, 3, 4)$  and

$$\begin{aligned} \rho &= \sqrt{0^2 + 3^2 + 4^2} = 5 \\ \theta &= \tan^{-1} \left( \frac{3}{0} \right) = \tan^{-1} (+\infty) = \frac{\pi}{2} \\ \phi &= \cos^{-1} \left( \frac{4}{5} \right) = \end{aligned}$$

are the spherical coordinates of this point.

□

6. Convert the point  $(1, \pi/4, 1)$  from cylindrical to Cartesian and spherical coordinates.

- Using the formulas appearing in the solution to Problem 22(a) we have We thus have

$$\begin{aligned}x &= r \cos \theta = 1 \cdot \cos \left( \frac{\pi}{4} \right) = \frac{\sqrt{2}}{2} \\y &= r \sin \theta = 1 \cdot \sin \left( \frac{\pi}{4} \right) = \frac{\sqrt{2}}{2} \\z &= z = 1\end{aligned}$$

for the Cartesian coordinates of the point  $(0,3,4)$ ; and so

$$\begin{aligned}\rho &= \sqrt{\left( \frac{\sqrt{2}}{2} \right)^2 + \left( \frac{\sqrt{2}}{2} \right)^2 + (1)^2} = \sqrt{2} \\ \theta &= \tan^{-1} \left( \frac{\frac{\sqrt{2}}{2}}{\frac{\sqrt{2}}{2}} \right) = \tan^{-1}(1) = \frac{\pi}{4} \\ \phi &= \cos^{-1} \left( \frac{1}{\sqrt{2}} \right) = \frac{\pi}{4}\end{aligned}$$

are the spherical coordinates of this point. □

7. Convert the point  $(1, \pi/2, \pi)$  from spherical to Cartesian and cylindrical coordinates.

- The Cartesian coordinates of this point can be obtained from the formulas given in the solution to Problem 22(a). We have and cylindrical coordinates

$$\begin{aligned}x &= \rho \cos \theta \sin \phi = (1) \cos \left( \frac{\pi}{2} \right) \sin(\pi) = 0 \\y &= \rho \sin \theta \sin \phi = (1) \sin \left( \frac{\pi}{2} \right) \sin(\pi) = 0 \\z &= \rho \cos \phi = (1) \cos(\pi) = -1\end{aligned}$$

Using these Cartesian coordinates we can easily compute the corresponding cylindrical coordinates:

$$\begin{aligned}r &= \sqrt{0^2 + 0^2} = 0 \\ \theta &= \tan^{-1} \left( \frac{0}{0} \right) = \text{undefined} \\ z &= z = -1\end{aligned}$$

Do not be upset by the fact that  $\theta$  is undefined. In polar coordinates,  $\theta$  is undefined (read inconsequential) for all points along the  $z$ -axis. □