## Math 3013.004 FIRST EXAM 10:30 - 11:45 am, Feb. 23, 1999

Name:\_\_\_\_\_

1. (5 pts) Compute the angle between the vectors  $\mathbf{u} = (1, 2, -1, 0)$  and  $\mathbf{v} = (1, 1, 2, 1)$ .

2. Let

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & -1 & 1 \end{bmatrix} \quad , \quad \mathbf{B} = \begin{bmatrix} 1 & 0 \\ 2 & -1 \\ 3 & 1 \end{bmatrix}$$

Compute the following matrices.

(a) (5 pts)  $\sqrt{2}\mathbf{A}$ 

(b) (5 pts) AB

(c) (5 pts) **BA** 

(d) (5 pts) A + 2B

3. Consider the following linear system

$$x_{1} - x_{2} + 2x_{3} = 1$$

$$2x_{1} + x_{2} + x_{3} = -1$$

$$3x_{1} + x_{2} + 2x_{3} = 3$$

$$x_{1} + x_{3} = 4$$

(a) (5 pts) Write down the corresponding augmented matrix and reduce it to row-echelon form.

(b) (5 pts) Reduce the augmented matrix further to **reduced** row-echelon form.

(c) (5 pts) Write down the solution of the original linear system.

4. (10 pts) Compute the inverse of

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 1 \\ 2 & 1 & 0 \\ 4 & 2 & 1 \end{bmatrix}$$

and verify that you have the correct inverse.

5. (10 pts) Use the fact that

to solve

$$\mathbf{A} = \begin{bmatrix} 1 & -1 & -1 \\ -2 & 3 & 0 \\ 1 & -1 & 0 \end{bmatrix} \implies \mathbf{A}^{-1} = \begin{bmatrix} 0 & 1 & 3 \\ 0 & 1 & 2 \\ -1 & 0 & 1 \end{bmatrix}$$
$$\begin{bmatrix} 1 & -1 & -1 \\ -2 & 3 & 0 \\ 1 & -1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

6. (10 pts) Determine if the set  $W = \{(x, y, z) \in \mathbb{R}^3 \mid y = x, z = 2x\}$  is a subspace of  $\mathbb{R}^3$ .

7. (10 pts) Find a basis for the solution set of the following homogeneous linear system.

$$\begin{array}{rcl} x_1 + 2x_2 + x_3 &=& 0 \\ x_1 + x_2 + 3x_3 &=& 0 \\ x_2 - 2x_3 &=& 0 \end{array}$$

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- 8. (20 pts) Mark each ot the following statements True or False. (Think carefully.)
- (a) If A, B and C are invertible  $n \times n$  matrices, then AC = BC implies A = B.
- (b) If **A** and **B** are invertible  $n \times n$  matrices, then AB = BA implies  $B = A^{-1}$ .
- (c) If a consistent linear system has more equations than unknowns, then there will be a unique solution.
- (d) If a square linear system Ax = 0 has only the trivial solution, then every linear system of the form Ax = b will have a unique solution.
- (e) If  $\mathbf{x}_1$  and  $\mathbf{x}_2$  are solutions of a consistent linear system  $\mathbf{A}\mathbf{x} = \mathbf{b}$ , then so is  $\mathbf{x}_1 + \mathbf{x}_2$ .
- (f) If **p** is a solution of  $\mathbf{A}\mathbf{x} = \mathbf{b}$  then every other solution can be written as  $\mathbf{x} = \mathbf{p} + \mathbf{h}$  where **h** is a solution of the corresponding homogeneous equation.
- (g) Every line in  $\mathbb{R}^2$  is a subspace of  $\mathbb{R}^2$ .
- (h) If  $\mathbf{v}_1$ ,  $\mathbf{v}_2$ , and  $\mathbf{v}_3$  are vectors in  $\mathbf{R}^3$ , then every vector in span $(\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3)$  can be represented as a linear combination of  $\mathbf{v}_1$ ,  $\mathbf{v}_2$ , and  $\mathbf{v}_3$ .
- (i) If every vector in a subspace W of  $\mathbb{R}^4$  can be represented as a linear combination of vectors  $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3 \in \mathbf{R}^4$ , then  $\mathbf{v}_1, \mathbf{v}_2$ , and  $\mathbf{v}_3$  form a basis for W.
- (j) A square linear system  $\mathbf{A}\mathbf{x} = \mathbf{b}$  has a unique solution if and only if  $\mathbf{A}$  is row-equivalent to the identity matrix.