

The Gram-Schmidt Algorithm

In the last lecture I showed how one could break a vector \mathbf{v} up into two orthogonal components; with one component lying in a given subspace W and another component lying in the subspace W^\perp that is orthogonal to W . The procedure was to

- choose a basis $B_W = \{\mathbf{b}_1, \dots, \mathbf{b}_k\}$ for W
- find a basis $B_{W^\perp} = \{\mathbf{b}_{k+1}, \dots, \mathbf{b}_n\}$ for W^\perp
- combine B_W with B_{W^\perp} to form a basis $B = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$ for \mathbb{R}^n
- find the coordinate vector \mathbf{v}_B of \mathbf{v} with respect to B and then throw away the components along the vectors $\{\mathbf{b}_{k+1}, \dots, \mathbf{b}_n\}$

Today we develop a more systematic approach that

THEOREM 17.1. *Let $\{\mathbf{v}_1, \dots, \mathbf{v}_k\}$ be a set of mutually orthogonal non-zero vectors. Then the vectors $\mathbf{v}_1, \dots, \mathbf{v}_k$ are linearly independent.*

Proof.

Suppose

$$(1) \quad c_1 \mathbf{v}_1 + \dots + c_k \mathbf{v}_k = \mathbf{0}$$

Then for each $i = 1, \dots, k$ we have

$$0 = \mathbf{0} \cdot \mathbf{v}_i = c_1 \mathbf{v}_i \cdot \mathbf{v}_1 + c_2 \mathbf{v}_i \cdot \mathbf{v}_2 + \dots + c_i \mathbf{v}_i \cdot \mathbf{v}_i + \dots + c_k \mathbf{v}_i \cdot \mathbf{v}_k = c_i \|\mathbf{v}_i\|^2 \implies c_i = 0$$

So we cannot satisfy (1) without each $c_i = 0$. Hence the vectors $\mathbf{v}_1, \dots, \mathbf{v}_k$ are linearly independent.

COROLLARY 17.2. *Any set of n mutually orthogonal non-zero vectors will be a basis for \mathbb{R}^n .*

Now suppose $B = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_k\}$ is a basis for some subspace W of \mathbb{R}^n . From this basis we can systematically construct an orthogonal basis for W ; that is a basis for which all the vectors are orthogonal.

Before we get started, let's recall that given any vectors \mathbf{a} and \mathbf{v} we have a decomposition of \mathbf{v}

$$(2) \quad \mathbf{v} = \mathbf{v}_\mathbf{a} + \mathbf{v}_{\mathbf{a}^\perp}$$

where $\mathbf{v}_\mathbf{a}$ is the component of \mathbf{v} along the direction of \mathbf{a} and $\mathbf{v}_{\mathbf{a}^\perp}$ is the component of \mathbf{v} along a direction perpendicular to \mathbf{v} . Moreover, we have the following formula for $\mathbf{v}_\mathbf{a}$

$$(3) \quad \mathbf{v}_\mathbf{a} = \frac{\mathbf{a} \cdot \mathbf{v}}{\mathbf{a} \cdot \mathbf{a}} \mathbf{a}$$

Combining (2) and (3) we have a formula for $\mathbf{v}_{\mathbf{a}^\perp}$ as well

$$\mathbf{v}_{\mathbf{a}^\perp} = \mathbf{v} - \frac{\mathbf{a} \cdot \mathbf{v}}{\mathbf{a} \cdot \mathbf{a}} \mathbf{a}$$

REMARK 17.3. Note that if \mathbf{a} and \mathbf{v} are linearly independent then $\mathbf{v}_{\mathbf{a}^\perp} \neq \mathbf{0}$: because it is a linear combination of two linearly independent vectors with at least one coefficient, the coefficient of \mathbf{v} , non-zero. Note also that from (3)

$$\mathbf{a} \cdot \mathbf{v}_{\mathbf{a}^\perp} = \mathbf{a} \cdot \mathbf{v} + \frac{\mathbf{a} \cdot \mathbf{v}}{\mathbf{a} \cdot \mathbf{a}} \mathbf{a} \cdot \mathbf{a} = 0$$

as expected.

Okay, here's how we generate an orthogonal basis. Set

$$\mathbf{o}_1 = \mathbf{b}_1$$

and then

$$\mathbf{o}_2 = \mathbf{b}_2 - \frac{\mathbf{o}_1 \cdot \mathbf{b}_2}{\mathbf{o}_1 \cdot \mathbf{o}_1} \mathbf{o}_1$$

By construction, \mathbf{o}_1 and \mathbf{o}_2 are perpendicular, non-zero and linearly independent. Now let

$$\mathbf{o}_3 = \mathbf{b}_3 - \frac{\mathbf{o}_1 \cdot \mathbf{b}_3}{\mathbf{o}_1 \cdot \mathbf{o}_1} \mathbf{o}_1 - \frac{\mathbf{o}_2 \cdot \mathbf{b}_3}{\mathbf{o}_2 \cdot \mathbf{o}_2} \mathbf{o}_2$$

The vector \mathbf{o}_3 is non-zero because it is a linear combination of the basis vectors \mathbf{b}_1 , \mathbf{b}_2 and \mathbf{b}_3 with at least one non-zero coefficient. Moreover

$$\begin{aligned} \mathbf{o}_1 \cdot \mathbf{o}_3 &= \mathbf{o}_1 \cdot \mathbf{b}_3 - \frac{\mathbf{o}_1 \cdot \mathbf{b}_3}{\mathbf{o}_1 \cdot \mathbf{o}_1} \mathbf{o}_1 \cdot \mathbf{o}_1 - \frac{\mathbf{o}_2 \cdot \mathbf{b}_3}{\mathbf{o}_2 \cdot \mathbf{o}_2} \mathbf{o}_1 \cdot \mathbf{o}_2 = \mathbf{o}_1 \cdot \mathbf{b}_3 - \mathbf{o}_1 \cdot \mathbf{b}_3 = 0 \\ \mathbf{o}_2 \cdot \mathbf{o}_3 &= \mathbf{o}_2 \cdot \mathbf{b}_3 - \frac{\mathbf{o}_1 \cdot \mathbf{b}_3}{\mathbf{o}_1 \cdot \mathbf{o}_1} \mathbf{o}_2 \cdot \mathbf{o}_1 - \frac{\mathbf{o}_2 \cdot \mathbf{b}_3}{\mathbf{o}_2 \cdot \mathbf{o}_2} \mathbf{o}_2 \cdot \mathbf{o}_2 = \mathbf{o}_2 \cdot \mathbf{b}_3 - \mathbf{o}_2 \cdot \mathbf{b}_3 = 0 \end{aligned}$$

and so $\{\mathbf{o}_1, \mathbf{o}_2, \mathbf{o}_3\}$ are mutually perpendicular non-zero vectors, and so linearly independent.

We can continue in this fashion to construct more and more linearly independent orthogonal vectors. For example,

$$\mathbf{o}_4 = \mathbf{b}_4 - \frac{\mathbf{o}_1 \cdot \mathbf{b}_4}{\mathbf{o}_1 \cdot \mathbf{o}_1} \mathbf{o}_1 - \frac{\mathbf{o}_2 \cdot \mathbf{b}_4}{\mathbf{o}_2 \cdot \mathbf{o}_2} \mathbf{o}_2 - \frac{\mathbf{o}_3 \cdot \mathbf{b}_4}{\mathbf{o}_3 \cdot \mathbf{o}_3} \mathbf{o}_3$$

In the end, when we reach \mathbf{b}_k this process terminates with

$$\mathbf{o}_k = \mathbf{b}_k - \frac{\mathbf{o}_1 \cdot \mathbf{b}_k}{\mathbf{o}_1 \cdot \mathbf{o}_1} \mathbf{o}_1 - \frac{\mathbf{o}_2 \cdot \mathbf{b}_k}{\mathbf{o}_2 \cdot \mathbf{o}_2} \mathbf{o}_2 - \dots - \frac{\mathbf{o}_{k-1} \cdot \mathbf{b}_k}{\mathbf{o}_{k-1} \cdot \mathbf{o}_{k-1}} \mathbf{o}_{k-1}$$

and we arrive at a set of k linearly independent, mutually orthogonal vectors $\{\mathbf{o}_1, \mathbf{o}_2, \dots, \mathbf{o}_k\}$

The basis $\{\mathbf{o}_1, \dots, \mathbf{o}_k\}$ obtained by the above algorithm, however, is not an **orthonormal basis**. That is to say, although mutually orthogonal by construction, the vectors \mathbf{o}_i do not necessarily have the length 1. In fact, it's rather unlikely that $\|\mathbf{o}_i\| = 1$. But there is an easy fix for this. All we have to do is divide each of the orthogonal basis vectors \mathbf{o}_i by their lengths $\|\mathbf{o}_i\| = \sqrt{\mathbf{o}_i \cdot \mathbf{o}_i}$ to get a set of k , mutually orthogonal, linearly independent vectors, all of length 1 :

$$\begin{aligned} \mathbf{o}_1 &\longrightarrow \mathbf{n}_1 = \frac{1}{\sqrt{\mathbf{o}_1 \cdot \mathbf{o}_1}} \mathbf{o}_1 \\ \mathbf{o}_2 &\longrightarrow \mathbf{n}_2 = \frac{1}{\sqrt{\mathbf{o}_2 \cdot \mathbf{o}_2}} \mathbf{o}_2 \\ &\vdots \\ \mathbf{o}_k &\longrightarrow \mathbf{n}_k = \frac{1}{\sqrt{\mathbf{o}_k \cdot \mathbf{o}_k}} \mathbf{o}_k \end{aligned}$$

EXAMPLE 17.4. Find a orthonormal basis for the subspace

$$W = \text{span}([1, -1, 1, 0, 0], [-1, 0, 0, 0, 1], [0, 0, 1, 0, 1])$$

of \mathbb{R}^5 .

- First we need a basis for W .

$$\begin{bmatrix} 1 & -1 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 \end{bmatrix}$$

This last matrix is in row echelon form with no non-zero rows. From this short calculation we see that the original three vectors are linearly independent and so will constitute a basis for W . We can thus use $B = \{\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3\}$ with

$$\begin{aligned} \mathbf{b}_1 &= [1, -1, 1, 0, 0] \\ \mathbf{b}_2 &= [-1, 0, 0, 0, 1] \\ \mathbf{b}_3 &= [0, 0, 1, 0, 1] \end{aligned}$$

as an initial basis to start the Gram-Schmidt orthogonalization process.

Thus, we set

$$\begin{aligned} \mathbf{o}_1 &= \mathbf{b}_1 = [1, -1, 1, 0, 0] \\ \implies \|\mathbf{o}_1\|^2 &= 3 \\ \implies \mathbf{n}_1 &= \left[\frac{1}{\sqrt{3}}, -\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, 0, 0 \right] \end{aligned}$$

Next we compute \mathbf{o}_2 ,

$$\begin{aligned} \mathbf{o}_2 &= \mathbf{b}_2 - \frac{\mathbf{o}_1 \cdot \mathbf{b}_2}{\mathbf{o}_1 \cdot \mathbf{o}_1} \mathbf{o}_1 \\ &= [-1, 0, 0, 0, 1] - \frac{(-1)}{3} [1, -1, 1, 0, 0] \\ &= \left[-\frac{2}{3}, -\frac{1}{3}, \frac{1}{3}, 0, 1 \right] \end{aligned}$$

We have

$$\begin{aligned} \|\mathbf{o}_2\|^2 &= \frac{4}{9} + \frac{1}{9} + \frac{1}{9} + 1 = \frac{5}{3} \\ \implies \mathbf{n}_2 &= \sqrt{\frac{3}{5}} \left[-\frac{2}{3}, -\frac{1}{3}, \frac{1}{3}, 0, 1 \right] \end{aligned}$$

Finally,

$$\begin{aligned} \mathbf{o}_3 &= \mathbf{b}_3 - \frac{\mathbf{o}_1 \cdot \mathbf{b}_3}{\mathbf{o}_1 \cdot \mathbf{o}_1} \mathbf{o}_1 - \frac{\mathbf{o}_2 \cdot \mathbf{b}_3}{\mathbf{o}_2 \cdot \mathbf{o}_2} \mathbf{o}_2 \\ &= [0, 0, 1, 0, 1] - \frac{(1)}{(3)} [[1, -1, 1, 0, 0]] - \frac{(1)}{(2)} [-1, 0, 0, 0, 1] \\ &= \left[\frac{1}{6}, \frac{1}{3}, \frac{2}{3}, 0, \frac{1}{2} \right] \end{aligned}$$

and

$$\|\mathbf{o}_3\|^2 = \frac{1}{36} + \frac{1}{9} + \frac{4}{9} + \frac{1}{4} = \frac{5}{6}$$

so

$$\mathbf{n}_3 = \sqrt{\frac{6}{5}} \left[\frac{1}{6}, \frac{1}{3}, \frac{2}{3}, 0, \frac{1}{2} \right]$$

Thus,

$$B' = \left\{ \left[\frac{1}{\sqrt{3}}, -\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, 0, 0 \right], \sqrt{\frac{3}{5}} \left[-\frac{2}{3}, -\frac{1}{3}, \frac{1}{3}, 0, 1 \right], \sqrt{\frac{6}{5}} \left[\frac{1}{6}, \frac{1}{3}, \frac{2}{3}, 0, \frac{1}{2} \right] \right\}$$

will be an orthonormal basis for W .